

ON A VARIANT OF THE ASYMPTOTIC PROCEDURE (FOR WEAKLY NONLINEAR AUTONOMOUS SYSTEMS)

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As well-known, usually, in the asymptotic (Krylov-Bogoliubov-Mitropolski) method, the full amplitude (a) of the first harmonic is used as variable in asymptotic expansions [1]. In the first approximation, the equations of stationary oscillations are rather simple, however, in higher approximation, these equations often become very complicated, especially when initial conditions are imposed.

In this article, a variant of the asymptotic procedure is presented and applied to determine stationary oscillations in weakly nonlinear autonomous system with given initial conditions. Instead of the full amplitude, the approximate amplitude of order ε^0 is used and by this, stationary oscillations can easily and successively be determined in each step of approximation, although various types of initial conditions may be imposed. It is interesting to note that the results obtained are identical with those given by the Poincaré method [2].

1. Systems under consideration - The usual asymptotic procedure

Consider weakly nonlinear autonomous oscillating systems described by following differential equations:

$$\ddot{x} + x = \varepsilon f(x), \quad (1.1)$$

$$\ddot{x} + x = \varepsilon f(x, \dot{x}), \quad (1.2)$$

where x is oscillatory variable; overdots denote differentiation with respect to time t ; 1 is own frequency; $f(x)$ and $f(x, \dot{x})$ -for simplicity-are polynomials of their variables; ε is a small formal parameter. The equation (1.1) represents weakly nonlinear conservative systems, the equation (1.2) represents weakly nonlinear self-excited systems. The problem of interest is to determine stationary oscillations (free or self-excited oscillations) satisfying initial conditions:

$$\text{for (1.1):} \quad x(0) = x_0, \quad \dot{x}(0) = 0, \quad (1.3)$$

$$\text{for (1.2):} \quad \dot{x}(0) = 0. \quad (1.4)$$

For the sake of comparison, the usual procedure of the asymptotic method is briefly recalled:

First, following asymptotic expansions are used

$$x = a \cos \psi + \varepsilon u_1(a, \psi) + \varepsilon^2 u_2(a, \psi) + \dots, \quad (1.5)$$

$$\dot{a} = \varepsilon A_1(a) + \varepsilon^2 A_2(a) + \dots, \quad (1.6)$$

$$\dot{\psi} = 1 + \varepsilon B_1(a) + \varepsilon^2 B_2(a) + \dots, \quad (1.7)$$

where a is the full amplitude of the first harmonic; ψ is phase angle; A_i, B_i ($i = 1, 2, \dots$) are functions of a ; and u_i ($i = 1, 2, \dots$) are functions of a and ψ , periodic with respect to ψ with period 2π .

Since a is the full amplitude of the first harmonic, u_i ($i = 1, 2, \dots$) do not contain any first harmonic.

Then, substituting (1.5) into (1.1) or (1.2), using (1.6), (1.7), equating the terms of like powers of ε yield

$$-2A_1 \sin \psi - 2aB_1 \cos \psi + \frac{\partial^2 u_1}{\partial \psi^2} + u_1 = f^{(1)}(a, \psi), \quad (1.8)$$

$$\begin{aligned} -2A_2 \sin \psi - 2aB_2 \cos \psi + \frac{\partial^2 u_2}{\partial \psi^2} + u_2 = f^{(2)}(a, \psi) = 2A_1 B_1 \sin \psi + aB_1 \frac{\partial B_1}{\partial a} \sin \psi \\ - A_1 \frac{\partial A_1}{\partial a} \cos \psi + aB_1^2 \cos \psi - 2A_1 \frac{\partial^2 u_1}{\partial \psi \partial a} - 2B_1 \frac{\partial^2 u_1}{\partial \psi^2} + \tilde{f}(a, \psi), \end{aligned} \quad (1.9)$$

where

$$\text{for (1.1) : } f^{(1)}(a, \psi) = f(a \cos \psi), \quad \tilde{f}(a, \psi) = u_1 \cdot f_x(a \cos \psi), \quad (1.10)$$

$$\text{for (1.2) : } f^{(1)}(q, \psi) = f(a \cos \psi, -a \sin \psi)$$

$$\begin{aligned} \tilde{f}(a, \psi) = u_1(a, \psi) \cdot f_x(a \cos \psi, -a \sin \psi) \\ + \left(A_1 \cos \psi - aB_1 \sin \psi + \frac{\partial u_1}{\partial \psi} \right) f_{\dot{x}}(a \cos \psi, -a \sin \psi), \end{aligned} \quad (1.11)$$

$f_x, f_{\dot{x}}$ are partial derivatives of the function f with respect to x, \dot{x} .

Finally, expanding $f^{(1)}(a, \psi), f^{(2)}(a, \psi)$ in Fourier series, equating the terms of like harmonics yield

$$f^{(i)}(a, \psi) = f_0^{(i)}(a) + \sum_{n=1}^{N_i} [S_n^{(i)}(a) \sin n\psi + C_n^{(i)}(a) \cos n\psi]; \quad N_i > 0, \text{ integer} \quad (1.12)$$

$$A_i(a) = -\frac{1}{2} S_1^{(i)}(a), \quad B_i(a) = -\frac{1}{2a} C_1^{(i)}(a), \quad (1.13)$$

$$\frac{\partial^2 u_i}{\partial \psi^2} + u_i = f_0^{(i)}(a) + \sum_{n=2}^{N_i} [S_n^{(i)}(a) \sin n\psi + C_n^{(i)}(a) \cos n\psi], \quad (1.14)$$

$$u_i(a, \psi) = f_0^{(i)}(a) - \sum_{n=2}^{N_i} \frac{1}{n^2 - 1} [S_n^{(i)}(a) \sin n\psi + C_n^{(i)}(a) \cos n\psi], \quad (1.15)$$

where $S_n^{(i)}(a) \equiv 0$ for the cases (1.1).

Let us determine stationary oscillation in the second approximation.

For (1.1): Since $A_1(a) \equiv 0$, $A_2(a) \equiv 0$, without initial condition, the amplitude a and the initial phase θ are arbitrary and we have

$$\begin{aligned} x &= a \cos \psi + \varepsilon \left\{ f_0^{(1)}(a) - \sum_{n=2}^{N_1} \frac{1}{n^2 - 1} C_n^{(1)}(a) \cos n\psi \right\}, \\ \psi &= \{1 + \varepsilon B_1(a) + \varepsilon^2 B_2(a)\}t + \theta. \end{aligned} \quad (1.16)$$

If the initial condition (1.3) are imposed, a and θ are determined by the equations:

$$\begin{aligned} x(0) &= a \cos \theta + \varepsilon \left\{ f_0^{(1)}(a) - \sum_{n=2}^{N_1} \frac{1}{n^2 - 1} C_n^{(1)}(a) \cos n\theta \right\} = x_0, \\ \frac{\partial x(a, \theta)}{\partial \psi} &= -a \sin \theta + \varepsilon \sum_{n=2}^{N_1} \frac{n}{n^2 - 1} C_n^{(1)}(a) \sin n\theta = 0. \end{aligned} \quad (1.17)$$

Stationary oscillation is stable with respect to a (not asymptotically)

For (1.2): The amplitude a is determined by the equation

$$\varepsilon A_1(a) + \varepsilon^2 A_2(a) = 0, \quad (1.18)$$

and, with regard that

$$x = a \cos \psi + \varepsilon \left\{ f_0^{(1)}(a) - \sum_{n=2}^{N_1} \frac{1}{n^2 - 1} [S_n^{(1)}(a) \sin n\psi + C_n^{(1)}(a) \cos n\psi] \right\}, \quad (1.19)$$

the initial phase θ is determined by the equation

$$\frac{\partial x(a, \theta)}{\partial \psi} = -a \sin \theta - \sum_{n=2}^{N_1} \frac{n}{n^2 - 1} [S_n^{(1)}(a) \cos n\theta - C_n^{(1)}(a) \sin n\theta] = 0. \quad (1.20)$$

The condition for asymptotic stability is

$$\varepsilon \frac{\partial A_1}{\partial a} + \varepsilon^2 \frac{\partial A_2}{\partial a} < 0. \quad (1.21)$$

2. Stationary oscillation from a variant of the asymptotic procedure

In this section, the problem of interest is treated by a variant of the asymptotic procedure.

First, a is considered now as the approximate (not full) amplitude of order ε^0 of the first harmonic. The asymptotic expansions of x , \dot{x} , ψ retain their forms (1.5), (1.6), (1.7) but the functions u_i ($i = 1, 2, \dots$) may contain the first harmonics $a_i \cos \psi + b_i \sin \psi$ of order ε^i where a_i , b_i are constants to be chosen. The presence of a_i , b_i modifies all the calculations in the second and higher approximations; however, as "compansion", a suitable choice of a_i , b_i allows us to consider the initial phase as zero, that is $\psi(0) = 0$.

Then, stationary oscillation is determined - not at the end but - successively in each step of approximation; this can be done by using two following requirements:

1 - The amplitude a (of stationary oscillation) is constant i.e. $\dot{a} = 0$ in each step of approximation; this means that, for every i , we have

$$A_i(a_*) = 0 \quad (i = 1, 2, \dots). \quad (2.1)$$

2 - Also in each step of approximation, the initial conditions must be satisfied.

For the initial condition $x(0) = x_0$, the amplitude of stationary oscillation should be taken

$$a = a_* = x_0 \quad (2.2)$$

and the functions u_i should be vanished at the initial moment, that is

$$u_i(a_*, \psi(0)) = u_i(a_*, 0) = 0. \quad (2.3)$$

For the initial condition $\dot{x}(0) = 0$, the partial derivative of u_i with respect to ψ at initial moment should be vanished, that is

$$\frac{\partial u_i(a_*, 0)}{\partial \psi} = 0. \quad (2.4)$$

In detail, for (1.1), in the first approximation, $x = a \cos \psi$ and since $A_1(a) \equiv 0$, we have $a = a_* = x_0$, the initial conditions $x(0) = x_0$, $\dot{x}(0) = 0$ are satisfied. The expression of $u_1(a, \psi)$ is of the form:

$$u_1(a, \psi) = f_0^{(1)}(a) - \sum_{n=2}^{N_1} \frac{1}{n^2 - 1} C_n^{(1)}(a) \cos n\psi + a_1 \cos \psi + b_1 \sin \psi. \quad (2.5)$$

Again, to satisfy the initial conditions (1.3), a_1 and b_1 should be taken

$$a_1 = a_{1*} = -f_0^{(1)}(a_*) + \sum_{n=2}^{N_1} \frac{1}{n^2 - 1} C_n^{(1)}(a_*); \quad b_1 = b_{1*} = 0. \quad (2.6)$$

Because of the presence of a_{1*} in $u_1(a, \psi)$, the expansion of $f^{(2)}(a, \psi)$ is modified

$$f^{(2)}(a, \psi) = \bar{f}_0^{(2)}(a) + \sum_{n=1}^{N_2} \bar{C}_n^{(2)}(a) \cos n\psi, \quad (2.7)$$

where $\bar{f}_0^{(2)}(a)$, $\bar{C}_n^{(2)}(a)$ differ from $f_0^{(2)}(a)$, $C_n^{(2)}(a)$.

In the second approximation

$$A_2(a) \equiv 0, \quad B_2(a) = -\frac{1}{2a} \bar{C}_1^{(2)}(a), \quad (2.8)$$

$$u_2(a, \psi) = \bar{f}_0^{(2)}(a) - \sum_{n=2}^{N_2} \frac{1}{n^2 - 1} \bar{C}_n^{(2)}(a) \cos n\psi + a_2 \cos \psi + b_2 \sin \psi, \quad (2.9)$$

where
$$a_2 = a_{2*} = -\bar{f}_0^{(2)}(a_*) + \sum_{n=2}^{N_2} \frac{1}{n^2 - 1} \bar{C}_n^{(2)}(a_*), \quad b_2 = b_{2*} = 0. \quad (2.10)$$

For (1.2): In the first approximation, the amplitude a_* of stationary oscillation is determined by the equation

$$\varepsilon A_1(a) = 0 \quad \text{i.e.} \quad S_1^{(1)}(a) = 0. \quad (2.11)$$

The expansion of $u_1(a, \psi)$ is:

$$u_1(a, \psi) = f_0^{(1)}(a) - \sum_{n=2}^{N_1} \frac{1}{n^2 - 1} [S_n^{(1)}(a) \sin n\psi + C_n^{(1)}(a) \cos n\psi] + a_1 \cos \psi + b_1 \sin \psi. \quad (2.12)$$

To satisfy the initial condition (1.4), b_1 should be chosen such that

$$\frac{\partial u_1(a_*, 0)}{\partial \psi} = 0 \quad \text{i.e.} \quad b_1 = b_{1*} = \sum_{n=2}^{N_1} \frac{n}{n^2 - 1} S_n^{(1)}(a_*). \quad (2.13)$$

As to a_1 , it can only be determined in the second approximation. Indeed, the expansion of $f^{(2)}(a, \psi)$ can be written as

$$f^{(2)}(a, \psi) = [\bar{f}_0^{(2)}(a) + a_1 f_0(a)] + \sum_{n=1}^{N_2} \left\{ [\bar{S}_n^{(2)}(a) + a_1 S_n(a)] \sin n\psi + [\bar{C}_n^{(2)}(a) + a_1 C_n(a)] \cos n\psi \right\} \quad (2.14)$$

and
$$A_2(a) = \frac{-1}{2} [\bar{S}_1^{(2)}(a) + a_1 S_1(a)], \quad B_2 = \frac{-1}{2a} [\bar{C}_1^{(2)}(a) + a_1 C_1(a)]. \quad (2.15)$$

Imposing on $A_2(a)$ the requirement $A_2(a_*) = 0$, we obtain

$$a_1 = a_{1*} = -\frac{\bar{S}_1^{(2)}(a_*)}{S_1(a_*)} \quad \text{on condition that } S_1(a_*) \neq 0. \quad (2.16)$$

Thus, in the second approximation, we have

$$x = a \cos \psi + \varepsilon \left\{ f_0^{(1)}(a) - \sum_{n=2}^{N_1} [S_n^{(1)}(a) \sin n\psi + C_n^{(1)}(a) \cos n\psi] + a_{1*} \cos \psi + b_{1*} \sin \psi \right\}, \quad (2.17)$$

$$\dot{a} = \varepsilon A_1(a) + \varepsilon^2 A_2(a) = -\frac{\varepsilon}{2} S_1^{(1)}(a) - \frac{\varepsilon^2}{2} \{ \bar{S}_1^{(2)}(a) + a_{1*} S_1(a) \}, \quad (2.18)$$

$$\dot{\psi} = 1 + \varepsilon B_1(a) + \varepsilon^2 B_2(a) = 1 - \frac{\varepsilon}{2a} C_1^{(1)}(a) - \frac{\varepsilon^2}{2a} \{ \bar{C}_1^{(2)}(a) + a_{1*} C_1(a) \}. \quad (2.19)$$

The amplitude a_* of stationary oscillation is given by (2.11) and the phase angle of stationary oscillation is $\psi(t) = \{1 + \varepsilon B_1(a_*) + \varepsilon^2 B_2(a_*)\}t$. Note that in (2.17),

(2.18), (2.19), $a = a(t)$ is the varying amplitude therefore, from (2.18), the condition for asymptotically stability can easily be established

$$\left(\varepsilon \frac{\partial A_1}{\partial a} + \varepsilon^2 \frac{\partial A_2}{\partial a} \right)_* < 0. \quad (2.20)$$

The expression of A_2 in (2.20) differs from that corresponding in (1.21). On the other hand, the left hand side of (2.20) is calculated with $a = a_*$ determined in the first approximation while the left hand side of (1.21) is calculated with a determined in the second approximation. Thus, (2.20)-being not identical with (1.21) - is more simple and that is just an advantage of the variant of the asymptotic method.

3. Comparison and example

The modified procedure already presented can be justified by comparing the results obtained in §2 with those given by the Poincaré method [2]. Indeed, for the case (1.2), introducing the new time τ

$$\tau = \omega t \quad (3.1)$$

the system (1.1), (1.2) are rewritten as

$$\omega^2 x'' + x = \varepsilon f(x, \omega x'), \quad (3.2)$$

$$x'(0) = 0, \quad (3.3)$$

where ω is the unknown frequency; primes denote differentiation with respect to τ .

Then both two unknowns x and ω are expanded in powers of ε that is

$$x = x_0 + \varepsilon x_1 + \varepsilon^2 x_2 + \dots, \quad (3.4)$$

$$\omega = 1 + \varepsilon \omega_1 + \varepsilon^2 \omega_2 + \dots \quad (3.5)$$

As to the initial condition (1.4), it is replaced by

$$x'_0(0) = 0, \quad (3.6)$$

$$x'_i(0) = 0, \quad (i = 1, 2, \dots). \quad (3.7)$$

Substituting (3.4), (3.5) into (3.2), expanding the right hand side in Taylor's series of ε , equating the terms of like powers of ε in the two sides yield

$$x''_0 + x_0 = 0, \quad (3.8)$$

$$x''_1 + x_1 + 2\omega_1 x''_0 = f(x_0, x'_0), \quad (3.9)$$

$$x''_2 + x_2 + 2\omega_2 x''_0 = -2\omega_1 x''_0 - \omega_1^2 x''_0 + x_1 f_x + (\omega_1 x'_0 + x'_1) f_x(x_0, x'_0), \quad (3.10)$$

... ..

The general solution of the differential equation (3.8) satisfying the initial condition (3.6) is

$$x_0 = a \cos \tau. \quad (3.11)$$

Substituting (3.11) into (3.9), (3.10) gives

$$x_1'' + x_1 - 2a\omega_1 \cos \tau = f(a \cos \tau_1 - a \sin \tau_1), \quad (3.12)$$

$$x_2'' + x_2 - 2a\omega_2 \cos \tau = 2a\omega_1 \cos \tau + a\omega_1^2 \cos \tau + x_1 f_x(a \cos \tau_1 - a \sin \tau_1) \\ + (-a\omega_1 \sin \tau + x_1') f_x'(a \cos \tau_1 - a \sin \tau), \quad (3.13)$$

... ..

Except the absence of the terms containing A_1, A_2 as factors, the difference between the equations (3.12), (3.13) and their corresponding ones (1.8), (1.9) is of formal character and consists only in the difference between the notations ($\tau = \omega t, \omega_i, x_i$ and $\psi = \omega t, B_i, u_i$). However, for steady state, $A_1(a_*) = A_2(a_*) = 0$; so, the equations (3.12), (3.13) lead to the same results as those in §2 i.e. the stationary oscillation obtained in §2 is identical with that determined by the Poincaré method.

As an illustration, consider the system

$$\ddot{x} + x = \varepsilon h(1 - x^2)\dot{x}, \quad h > 0.$$

In the first approximation we have:

$$-2A_1 \sin \psi - 2aB_1 \cos \psi + \frac{\partial^2 u_1}{\partial \psi^2} + u_1 = h(1 - a^2 \cos^2 \psi)(-a \sin \psi)$$

$$= -ha \left(1 - \frac{a^2}{4}\right) \sin \psi + \frac{ha^3}{4} \sin 3\psi,$$

$$A_1(a) = \frac{1}{2}ha \left(1 - \frac{a^2}{4}\right), \quad B_1 = 0, \quad a_* = 2,$$

$$u_1(a, \psi) = -\frac{ha^3}{32} \sin 3\psi + a_1 \cos \psi + b_1 \sin \psi,$$

$$\frac{\partial u_1}{\partial \psi} = -\frac{3ha^3}{32} \cos 3\psi - a_1 \sin \psi + b_1 \cos \psi, \quad b_1 = \frac{3ha^3}{32} = \frac{3h}{4}.$$

In the second approximation, we have:

$$-2A_2 \sin \psi - 2aB_2 \cos \psi + \frac{\partial^2 u_2}{\partial \psi^2} + u_2 = -A_1 \frac{\partial A_1}{\partial a} \cos \psi - 2A_1 \frac{\partial^2 u_1}{\partial \psi \partial a} \\ + u_1 ha^2 \sin 2\psi + \left(A_1 \cos \psi + \frac{\partial u_1}{\partial \psi}\right) h(1 - a^2 \cos^2 \psi) \\ = ha_1 \left(\frac{5a^2}{4} - 1\right) \sin \psi + \left\{ \frac{h^2 a^5}{128} + \frac{3h^2}{4} \left(1 - \frac{a^2}{4}\right) - A_1 \frac{\partial A_1}{\partial a} + A_1 h \left(1 - \frac{3a^2}{4}\right) \right\} \cos \psi \\ + \text{higher harmonics,}$$

$$A_2 = -\frac{ha_1}{2} \left(\frac{5a^2}{4} - 1 \right),$$

$$B_2 = -\frac{1}{2a} \left\{ \frac{h^2 a^5}{128} + \frac{3h^2}{4} + \frac{3h^2}{4} \left(1 - \frac{a^2}{4} \right) - A_1 \frac{\partial A_1}{\partial a} + A_1 h \left(1 - \frac{3a^2}{4} \right) \right\}.$$

We choose $a_1 = 0$ so that $A_2(a) \equiv 0$. Thus, in the second approximation the expression of x is

$$x = 2 \cos \psi + \varepsilon \frac{3h}{4} \sin \psi - \varepsilon \frac{h}{4} \sin 3\psi$$

and the condition of stability is

$$\left(\varepsilon \frac{\partial A_1}{\partial a} \right)_* = -\varepsilon \frac{ha^2}{4} = -\varepsilon h < 0 \quad \text{i.e.} \quad h > 0.$$

Conclusion

The variant of the asymptotic procedure above presented can be used for studying weakly nonlinear systems with given initial conditions. The determination as well as the stability study of stationary oscillation is rather simple, especially for higher approximation. The results obtained are identical with those given by the Poincaré method.

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MỘT BIẾN THỂ CỦA TRÌNH TỰ TIỆM CẬN (HỆ ÔTÔNÔM PHI TUYẾN YẾU)

Hệ ôtonôm phi tuyến yếu được khảo sát nhờ một biến thể của trình tự tiệm cận. Thay cho biên độ đầy đủ, biên độ ở xấp xỉ ε^0 của ác môníc thứ nhất được sử dụng trong khai triển tiệm cận. Việc xác định cũng như việc khảo sát ổn định của chế độ dừng có phần đơn giản hơn, nhất là ở xấp xỉ bậc cao. Các kết quả thu được trùng với các kết quả tương ứng trong phương pháp Poincaré.